NAG Fortran Library Routine Document

F07HVF (CPBRFS/ZPBRFS)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

F07HVF (CPBRFS/ZPBRFS) returns error bounds for the solution of a complex Hermitian positivedefinite band system of linear equations with multiple right-hand sides, AX = B. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Specification

```
SUBROUTINE F07HVF(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X,1LDX, FERR, BERR, WORK, RWORK, INFO)ENTRYcpbrfs(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X,1LDX, FERR, BERR, WORK, RWORK, INFO)INTEGERN, KD, NRHS, LDAB, LDAFB, LDB, LDX, INFOrealFERR(*), BERR(*), RWORK(*)complexAB(LDAB,*), AFB(LDAFB,*), B(LDB,*), X(LDX,*), WORK(*)CHARACTER*1UPLO
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine returns the backward errors and estimated bounds on the forward errors for the solution of a complex Hermitian positive-definite band system of linear equations with multiple right-hand sides AX = B. The routine handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of the routine in terms of a single right-hand side b and solution x.

Given a computed solution x, the routine computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

 $|\delta a_{ij}| \le \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \le \beta |b_i|.$

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where \hat{x} is the true solution.

For details of the method, see the F07 Chapter Introduction.

4 References

Golub G H and van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

C	i ui uiiotoi ș
1:	UPLO – CHARACTER*1 Input
	On <i>entry</i> : indicates whether the upper or lower triangular part of A is stored and how A has been factorized, as follows:
	if UPLO = 'U', the upper triangular part of A is stored and A is factorized as $U^{H}U$, where U is upper triangular;
	if UPLO = 'L', the lower triangular part of A is stored and A is factorized as LL^H , where L is lower triangular.
	Constraint: $UPLO = 'U'$ or 'L'.
2:	N – INTEGER Input
	On entry: n, the order of the matrix A.
	Constraint: $N \ge 0$.
3:	KD – INTEGER Input
	On entry: k, the number of super-diagonals or sub-diagonals of the matrix A.
	Constraint: $KD \ge 0$.
4:	NRHS – INTEGER Input
	On entry: r, the number of right-hand sides.
	Constraint: NRHS ≥ 0 .
5:	AB(LDAB,*) – <i>complex</i> array Input
	Note: the second dimension of the array AB must be at least $max(1, N)$.
	On entry: the n by n original Hermitian positive-definite band matrix A as supplied to F07HRF (CPBTRF/ZPBTRF).
6:	LDAB – INTEGER Input
	<i>On entry</i> : the first dimension of the array AB as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.
	Constraint: $LDAB \ge KD + 1$.
7:	AFB(LDAFB,*) – <i>complex</i> array Input
	Note: the second dimension of the array AFB must be at least $max(1, N)$.
	On entry: the Cholesky factor of A, as returned by F07HRF (CPBTRF/ZPBTRF).
8:	LDAFB – INTEGER Input
	<i>On entry</i> : the first dimension of the array AFB as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.
	<i>Constraint</i> : $LDAFB \ge KD + 1$.
9:	B(LDB,*) – <i>complex</i> array Input
	Note: the second dimension of the array B must be at least $max(1, NRHS)$.
	On entry: the n by r right-hand side matrix B .

LDB - INTEGER

10:

Input On entry: the first dimension of the array B as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.

Constraint: LDB $\geq \max(1, N)$.

X(LDX,*) – *complex* array 11:

Note: the second dimension of the array X must be at least max(1, NRHS).

On entry: the n by r solution matrix X, as returned by F07HSF (CPBTRS/ZPBTRS).

On exit: the improved solution matrix X.

LDX – INTEGER 12:

> On entry: the first dimension of the array X as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.

Constraint: LDX > max(1, N).

FERR(*) - *real* array 13:

Note: the dimension of the array FERR must be at least max(1, NRHS).

On exit: FERR(j) contains an estimated error bound for the *j*th solution vector, that is, the *j*th column of X, for $j = 1, 2, \ldots, r$.

14: BERR(*) - *real* array

Note: the dimension of the array BERR must be at least max(1, NRHS).

On exit: BERR(j) contains the component-wise backward error bound β for the jth solution vector, that is, the *j*th column of X, for j = 1, 2, ..., r.

WORK(*) - *complex* array 15:

Note: the dimension of the array WORK must be at least max(1, 2 * N).

RWORK(*) - real array 16:

Note: the dimension of the array RWORK must be at least max(1, N).

17: INFO - INTEGER

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 **Error Indicators and Warnings**

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

Output

Output

Input

Input/Output

Workspace

Workspace

Output

8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of 32nk real floatingpoint operations. Each step of iterative refinement involves an additional 48nk real operations. This assumes $n \gg k$. At most 5 steps of iterative refinement are performed, but usually only 1 or 2 steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form Ax = b; the number is usually 5 and never more than 11. Each solution involves approximately 16nk real operations.

The real analogue of this routine is F07HHF (SPBRFS/DPBRFS).

9 Example

To solve the system of equations AX = B using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 9.39 + 0.00i & 1.08 - 1.73i & 0.00 + 0.00i & 0.00 + 0.00i \\ 1.08 + 1.73i & 1.69 + 0.00i & -0.04 + 0.29i & 0.00 + 0.00i \\ 0.00 + 0.00i & -0.04 - 0.29i & 2.65 + 0.00i & -0.33 + 2.24i \\ 0.00 + 0.00i & 0.00 + 0.00i & -0.33 - 2.24i & 2.17 + 0.00i \end{pmatrix}$$

and

$$B = \begin{pmatrix} -12.42 + 68.42i & 54.30 - 56.56i \\ -9.93 + 0.88i & 18.32 + 4.76i \\ -27.30 - 0.01i & -4.40 + 9.97i \\ 5.31 + 23.63i & 9.43 + 1.41i \end{pmatrix}$$

Here A is Hermitian positive-definite, and is treated as a band matrix, which must first be factorized by F07HRF (CPBTRF/ZPBTRF).

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO7HVF Example Program Text
*
*
     Mark 15 Release. NAG Copyright 1991.
*
      .. Parameters ..
     INTEGER
                       NIN, NOUT
     PARAMETER
                       (NIN=5,NOUT=6)
     complex
                       ZERO
     PARAMETER
                       (ZERO = (0.0e0, 0.0e0))
     INTEGER
                     NMAX, NRHMAX, KDMAX, LDAB, LDAFB, LDB, LDX
     PARAMETER
                      (NMAX=8, NRHMAX=NMAX, KDMAX=8, LDAB=KDMAX+1,
     +
                       LDAFB=KDMAX+1,LDB=NMAX,LDX=NMAX)
      .. Local Scalars ..
                      I, IFAIL, INFO, J, KD, N, NRHS
     INTEGER
     CHARACTER
                      UPLO
      .. Local Arrays ..
*
     complex
                       AB(LDAB,NMAX), AFB(LDAFB,NMAX), B(LDB,NRHMAX),
                       WORK(2*NMAX), X(LDX,NMAX)
     real
                      BERR(NRHMAX), FERR(NRHMAX), RWORK(NMAX)
     CHARACTER
                     CLABS(1), RLABS(1)
      .. External Subroutines .
*
                      cpbrfs, cpbtrf, cpbtrs, F06TFF, F06THF, X04DBF
     EXTERNAL
      .. Intrinsic Functions .
*
     INTRINSIC
                      MAX, MIN
*
      .. Executable Statements ..
     WRITE (NOUT, *) 'FO7HVF Example Program Results'
     Skip heading in data file
     READ (NIN, *)
     READ (NIN, *) N, KD, NRHS
     IF (N.LE.NMAX .AND. KD.LE.KDMAX .AND. NRHS.LE.NRHMAX) THEN
```

```
*
          Set A to zero to avoid referencing uninitialized elements
*
*
          CALL F06THF('General', KD+1, N, ZERO, ZERO, AB, LDAB)
*
          Read A and B from data file, and copy A to AFB and B to X
+
          READ (NIN, *) UPLO
          IF (UPLO.EQ.'U') THEN
             DO 20 I = 1, N
                READ (NIN, \star) (AB(KD+1+I-J,J), J=I, MIN(N, I+KD))
   20
             CONTINUE
          ELSE IF (UPLO.EQ.'L') THEN
             DO 40 I = 1, N
                READ (NIN, \star) (AB(1+I-J,J), J=MAX(1,I-KD),I)
   40
             CONTINUE
          END IF
          READ (NIN, \star) ((B(I,J), J=1, NRHS), I=1, N)
          CALL F06TFF('General', KD+1, N, AB, LDAB, AFB, LDAFB)
          CALL F06TFF('General', N, NRHS, B, LDB, X, LDX)
*
*
          Factorize A in the array AFB
*
          CALL cpbtrf(UPLO, N, KD, AFB, LDAFB, INFO)
*
          WRITE (NOUT, *)
          IF (INFO.EQ.0) THEN
*
             Compute solution in the array X
*
*
             CALL cpbtrs(UPLO, N, KD, NRHS, AFB, LDAFB, X, LDX, INFO)
*
             Improve solution, and compute backward errors and
*
*
             estimated bounds on the forward errors
*
             CALL cpbrfs(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X, LDX,
                           FERR, BERR, WORK, RWORK, INFO)
     +
*
*
             Print solution
             IFAIL = 0
             CALL X04DBF('General',' ',N,NRHS,X,LDX,'Bracketed','F7.4',
'Solution(s)','Integer',RLABS,'Integer',CLABS,
     +
                           80,0,IFAIL)
     +
             WRITE (NOUT, *)
             WRITE (NOUT,*) 'Backward errors (machine-dependent)'
             WRITE (NOUT, 99999) (BERR(J), J=1, NRHS)
             WRITE (NOUT, *)
               'Estimated forward error bounds (machine-dependent)'
     +
             WRITE (NOUT, 99999) (FERR(J), J=1, NRHS)
          ELSE
             WRITE (NOUT, *) 'A is not positive-definite'
          END IF
      END IF
      STOP
99999 FORMAT ((5X, 1P, 4(e11.1, 7X)))
      END
```

9.2 Program Data

```
      F07HVF Example Program Data
      4 1 2
      :Values of N, KD and NRHS

      'L'
      :Value of UPLO

      ( 9.39, 0.00)
      ( 1.08, 1.73) ( 1.69, 0.00)
      :Value of UPLO

      ( -0.04, -0.29) ( 2.65, 0.00)
      ( -0.33, -2.24) ( 2.17, 0.00) :End of matrix A

      ( -12.42,68.42) (54.30, -56.56)
      ( -9.93, 0.88) (18.32, 4.76)

      ( -27.30, -0.01) (-4.40, 9.97)
      ( 5.31,23.63) ( 9.43, 1.41)
```

9.3 Program Results

```
F07HVF Example Program Results

Solution(s)

1 (-1.0000, 8.0000) ( 5.0000,-6.0000)

2 ( 2.0000,-3.0000) ( 2.0000, 3.0000)

3 (-4.0000,-5.0000) (-8.0000, 4.0000)

4 ( 7.0000, 6.0000) (-1.0000,-7.0000)

Backward errors (machine-dependent)

4.1E-17 6.0E-17

Estimated forward error bounds (machine-dependent)

3.1E-14 2.9E-14
```